

Convexity

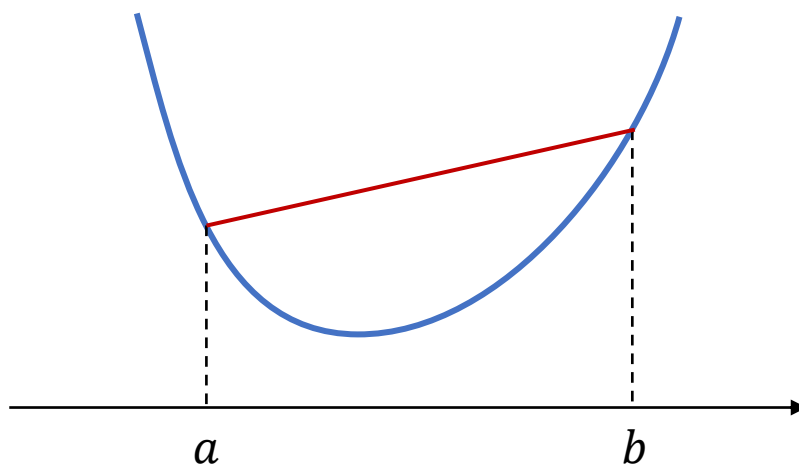
Hao-Wen Dong

Material based on Intro to Machine Learning (CSE 251A), Fall 2021

Definition – Convex function

- A function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is *convex* if for all $a, b \in \mathbb{R}^d$ and $0 < \theta < 1$,

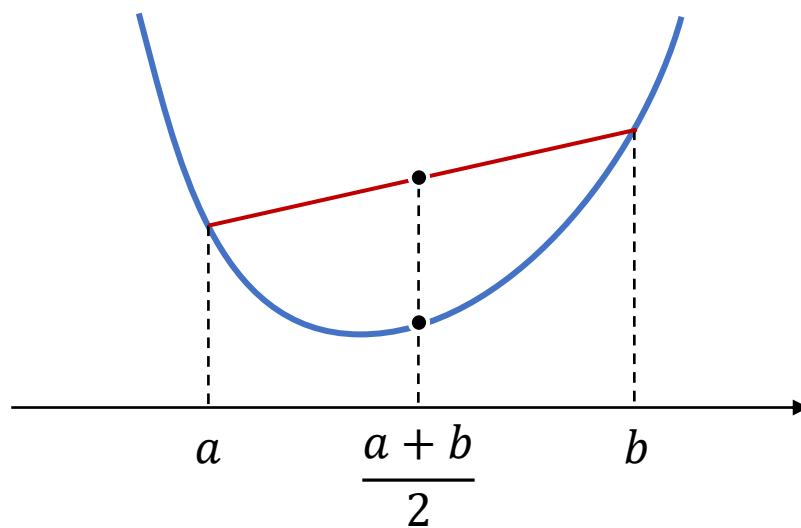
$$f(\theta a + (1 - \theta)b) \leq \theta f(a) + (1 - \theta)f(b)$$



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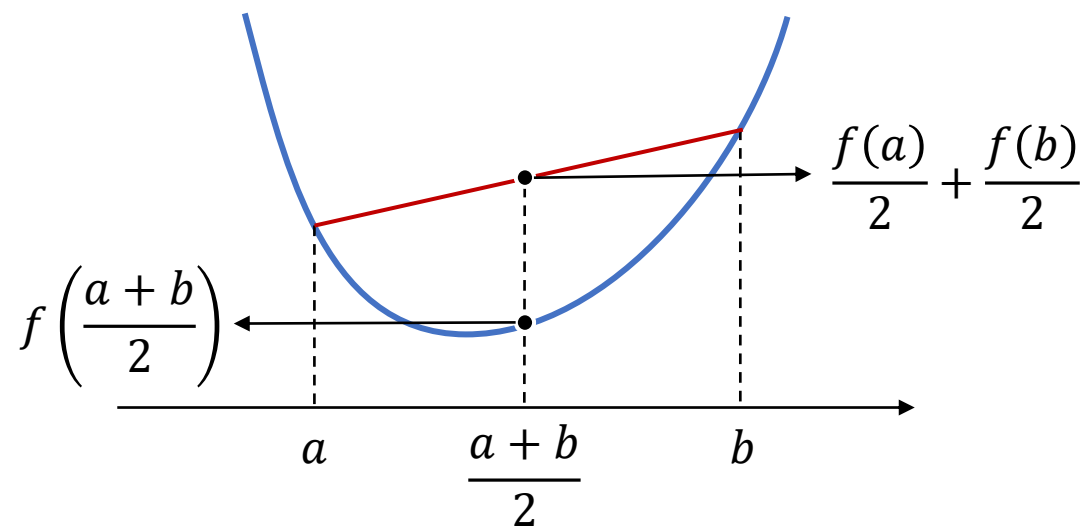
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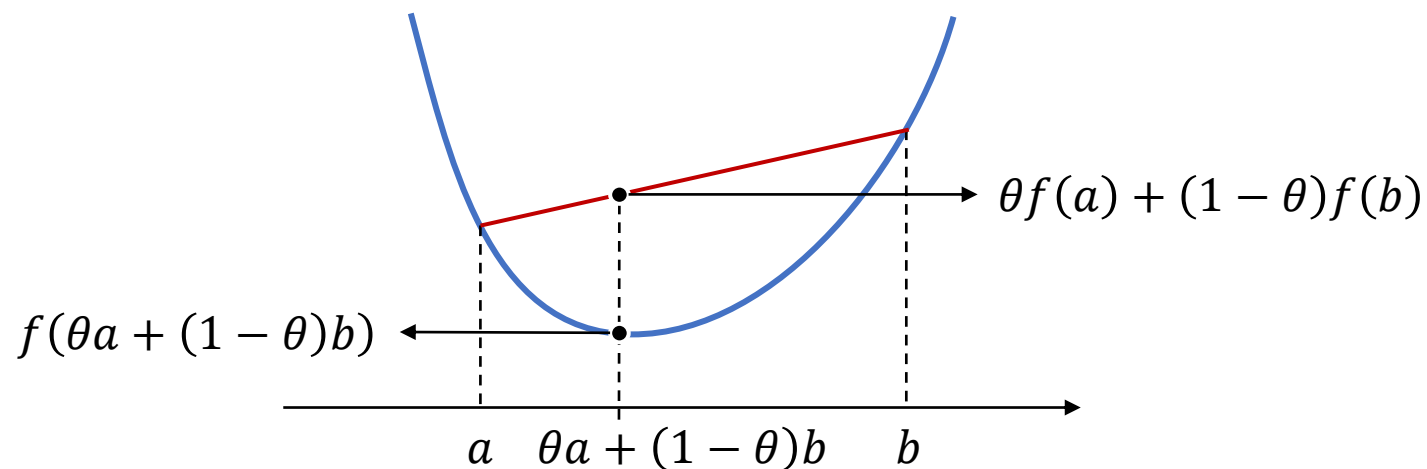
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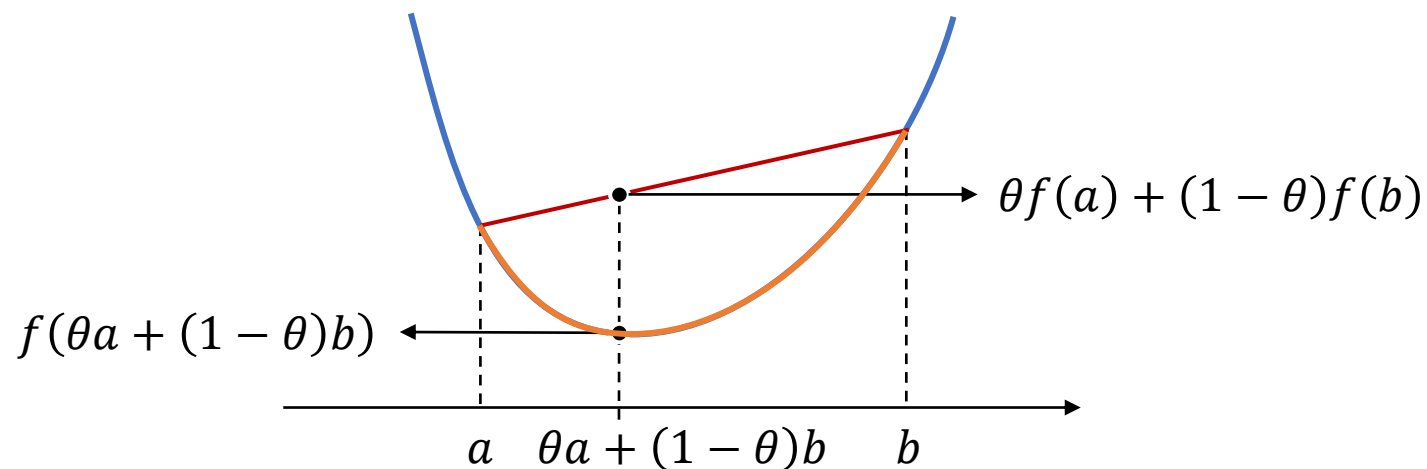
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Definition – Strictly convex function

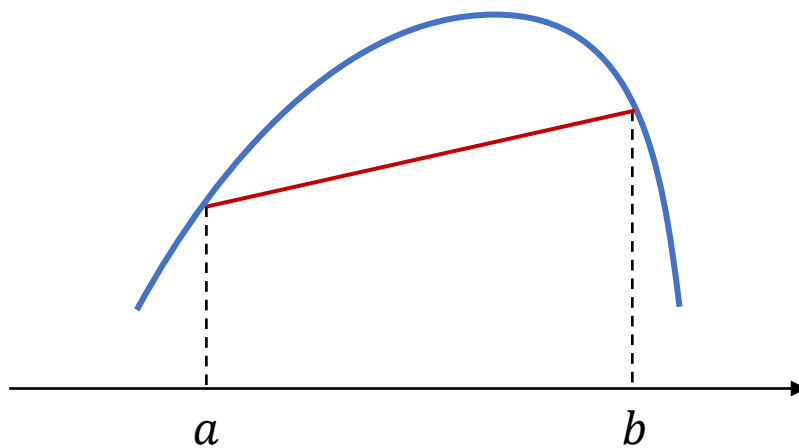
- A function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is *strictly convex* if for all $a \neq b \in \mathbb{R}^d$ and $0 < \theta < 1$,

$$f(\theta a + (1 - \theta)b) < \theta f(a) + (1 - \theta)f(b)$$

Definition – Concave function

- A function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is *concave* if for all $a, b \in \mathbb{R}^d$ and $0 < \theta < 1$,

$$f(\theta a + (1 - \theta)b) \geq \theta f(a) + (1 - \theta)f(b)$$



Properties of a convex function

- f is convex $\Leftrightarrow -f$ is concave
- f, g are both convex $\Rightarrow f + g$ is convex
- f, g are both convex $\Rightarrow \max(f, g)$ is convex

Second-derivative test for convexity

- A function $f: \mathbb{R} \rightarrow \mathbb{R}$ is convex if its **second derivative is nonnegative everywhere**
 - Example: $f(x) = x^2$

Second-derivative test for convexity

- How about a *multivariate* function $f: \mathbb{R}^d \rightarrow \mathbb{R}$?

Second-derivative test for convexity

- How about a *multivariate* function $f: \mathbb{R}^d \rightarrow \mathbb{R}$?
- A function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is convex if its **matrix of second derivatives is positive semidefinite** everywhere

First derivative of multivariate functions

- For a function $f: \mathbb{R}^d \rightarrow \mathbb{R}$, its first derivative is a vector with d entries, called the *gradient*

$$\nabla f(z) = \begin{bmatrix} \frac{\partial f}{\partial z_1} \\ \vdots \\ \frac{\partial f}{\partial z_d} \end{bmatrix}$$

First derivative of multivariate functions

- For a function $f: \mathbb{R}^d \rightarrow \mathbb{R}$, its second derivative is a $d \times d$ matrix, called the *Hessian* matrix

$$H_f = \begin{bmatrix} \frac{\partial f}{\partial z_1 \partial z_1} & \cdots & \frac{\partial f}{\partial z_1 \partial z_d} \\ \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial z_d \partial z_1} & \cdots & \frac{\partial f}{\partial z_d \partial z_d} \end{bmatrix}$$

- It's the Jacobian matrix of $\nabla f(z)$

Second-derivative test for convexity

- A function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is convex if its Hessian is positive semidefinite everywhere

Positive semidefinite (PSD)

- A symmetric matrix M is *positive semidefinite* if for all $z \in \mathbb{R}^d$

$$z^T M z \geq 0$$

Positive semidefinite (PSD)

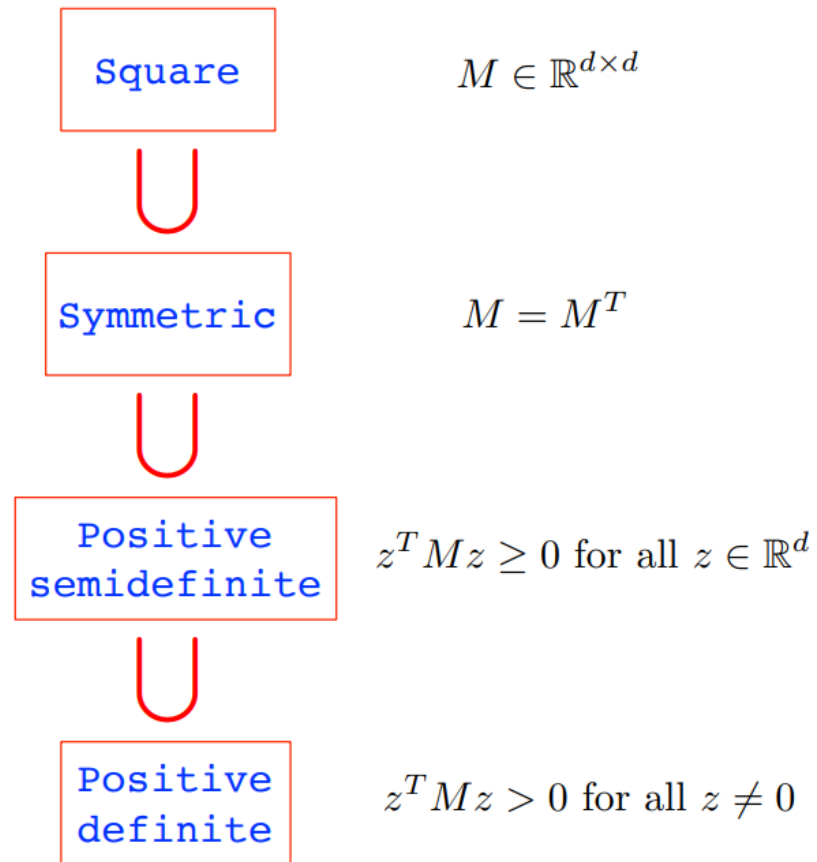
- A symmetric matrix M is *positive semidefinite* if for all $z \in \mathbb{R}^d$

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- Note that

$$z^T M z = \sum_{i,j=1}^d M_{ij} z_i z_j$$

A hierarchy of square matrices



Positive semidefinite (PSD)

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For any $z = \begin{bmatrix} z_1 \\ z_2 \end{bmatrix}$, we have

$$z^T M z = [z_1 \quad z_2] \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = [z_1 + z_2 \quad z_1 + z_2] \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = (z_1 + z_2)^2 \geq 0$$

Positive semidefinite (PSD)

- A symmetric matrix M is *positive semidefinite* if for all $z \in \mathbb{R}^d$

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- Is $M = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ positive semidefinite?

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For any $z = \begin{bmatrix} z_1 \\ z_2 \end{bmatrix}$, we have

$$z^T M z = \begin{bmatrix} z_1 & z_2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} z_1 + 2z_2 & 2z_1 + z_2 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = z_1^2 + 5z_1z_2 + z_2^2$$

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Recall: a matrix corresponds to a *linear transformation*

A geometric view of PSD: Any transformed vector Mz must have a nonnegative scalar projection on the original vector z .

In this case, $Mz = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ is in the opposite direction to $z = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$.

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- When is a diagonal matrix PSD?

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- When is a diagonal matrix PSD?

Suppose we have a diagonal matrix $M = \text{diag}(a_1, a_2, \dots, a_d)$, then we have

$$z^T M z = [z_1 \quad \dots \quad z_d] \begin{bmatrix} a_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & a_d \end{bmatrix} \begin{bmatrix} z_1 \\ \vdots \\ z_d \end{bmatrix} = [a_1 z_1 \quad \dots \quad a_d z_d] \begin{bmatrix} z_1 \\ \vdots \\ z_d \end{bmatrix} = a_1 z_1^2 + \dots + a_d z_d^2$$

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- When is a diagonal matrix PSD? *When all its elements are nonnegative*

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$$z^T M z = [z_1 \quad \dots \quad z_d] \begin{bmatrix} a_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & a_d \end{bmatrix} \begin{bmatrix} z_1 \\ \vdots \\ z_d \end{bmatrix} = [a_1 z_1 \quad \dots \quad a_d z_d] \begin{bmatrix} z_1 \\ \vdots \\ z_d \end{bmatrix} = a_1 z_1^2 + \dots + a_d z_d^2$$

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- Is $f(z) = \|z\|^2$ convex?

$$f(z) = \|z\|^2 = \sum_{i=1}^d z_i^2,$$
$$\nabla f(z) = \begin{bmatrix} \frac{\partial f}{\partial z_1} \\ \vdots \\ \frac{\partial f}{\partial z_d} \end{bmatrix} = \begin{bmatrix} 2z_1 \\ \vdots \\ 2z_d \end{bmatrix} = 2z,$$
$$H_f = \begin{bmatrix} \frac{\partial f}{\partial z_1 \partial z_1} & \cdots & \frac{\partial f}{\partial z_1 \partial z_d} \\ \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial z_d \partial z_1} & \cdots & \frac{\partial f}{\partial z_d \partial z_d} \end{bmatrix} = \begin{bmatrix} 2 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 2 \end{bmatrix} = 2I_d$$

Second-derivative test for convexity

- A function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ is convex if its Hessian is positive semidefinite everywhere
- Is $f(z) = \|z\|^2$ convex? **Yes!**

$$f(z) = \|z\|^2 = \sum_{i=1}^d z_i^2,$$

$$\nabla f(z) = \begin{bmatrix} \frac{\partial f}{\partial z_1} \\ \vdots \\ \frac{\partial f}{\partial z_d} \end{bmatrix} = \begin{bmatrix} 2z_1 \\ \vdots \\ 2z_d \end{bmatrix} = 2z, \quad H_f = \begin{bmatrix} \frac{\partial f}{\partial z_1 \partial z_1} & \cdots & \frac{\partial f}{\partial z_1 \partial z_d} \\ \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial z_d \partial z_1} & \cdots & \frac{\partial f}{\partial z_d \partial z_d} \end{bmatrix} = \begin{bmatrix} 2 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 2 \end{bmatrix} = 2I_d$$